

Approach to Modeling Boundary Layer Ingestion using a Fully Coupled Propulsion-RANS Model

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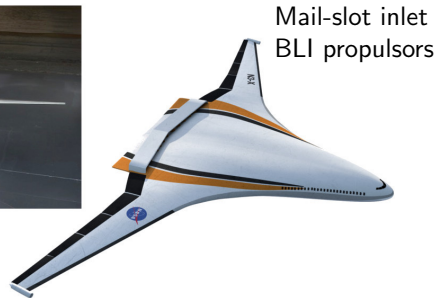
Boundary Layer Ingestion (BLI) offers between 5% and 12% fuel burn savings



Aft-mounted
BLI propulsor



Aft-mounted BLI engines



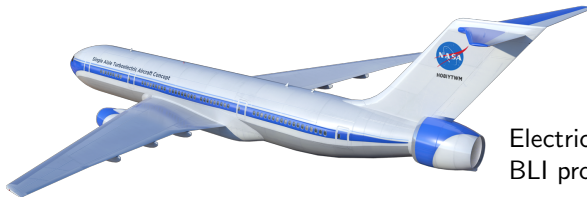
Mail-slot inlet
BLI propulsors

NASA's Starc-ABL configuration applies BLI to a traditional airframe

Tube-with-wings configuration

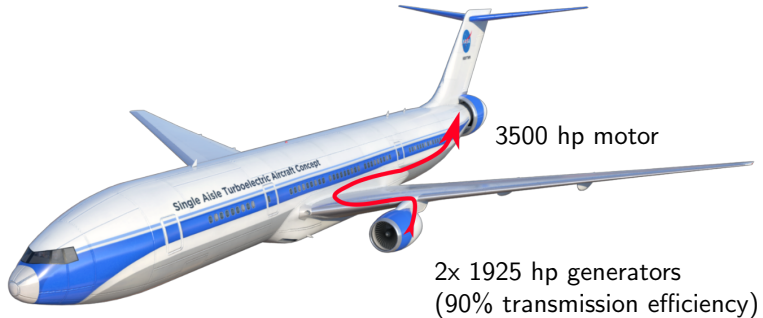


Under-wing engines
and generator



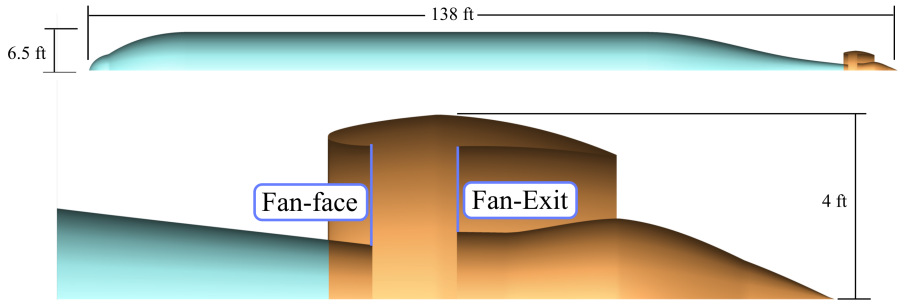
Electric
BLI propulsor

The BLI propulsor is powered by an electric motor delivering a constant 3500 hp



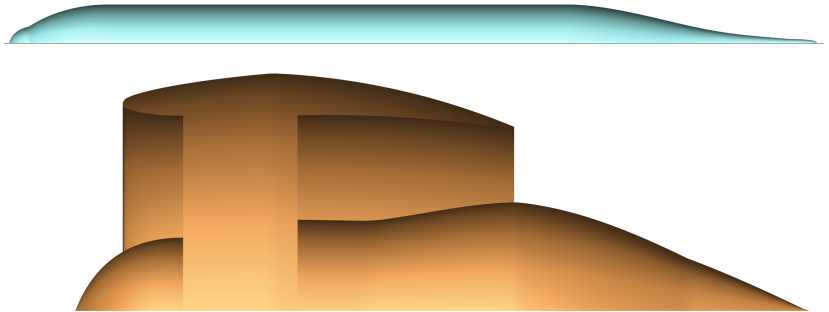
Turboelectric propulsion system has an electric BLI propulsor powered by generators mounted on the under-wing turbofans

We simplified the configuration to focus on the coupled performance of the BLI propulsor



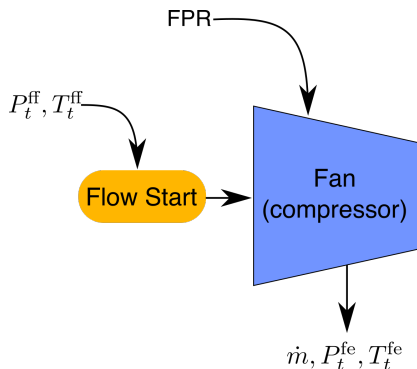
- Loosely based on 737 fuselage dimensions
- Removed wing, tail, and under-wing engines to simplify the analysis

BLI propulsor performance was
compared to a podded configuration



Exact same propulsor geometry, including inlet,
was used for both BLI and podded configurations

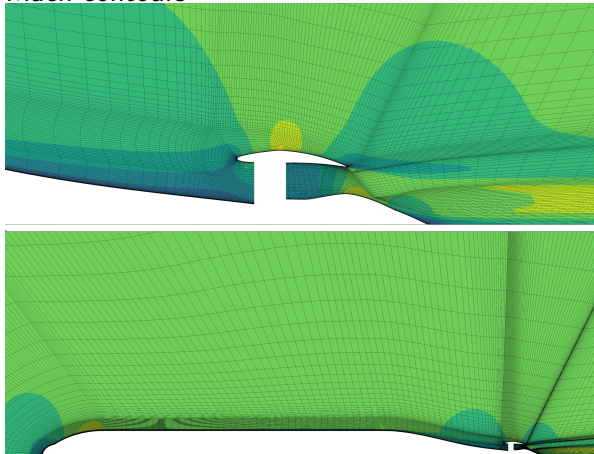
The propulsion analysis was a 1D thermodynamic cycle model



- modeled with pyCycle, a modular propulsion cycle tool built in the OpenMDAO framework

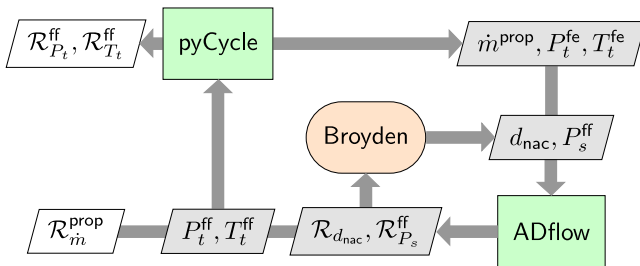
The aerodynamic analysis was a 2D axisymmetric RANS model

Mach contours



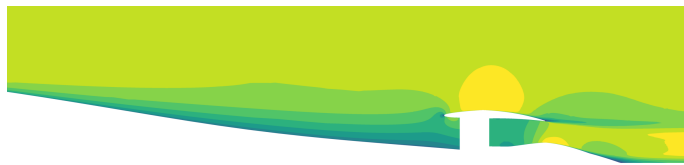
- ~170,000 cell mesh
- a single solve takes ~2 minutes

The analyses were coupled via a Gauss-Seidel iteration

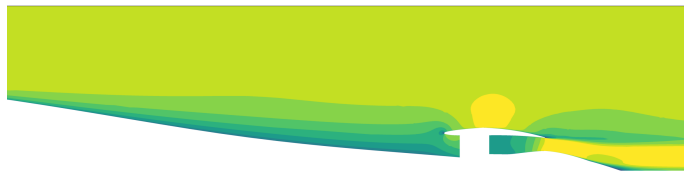


- **pyCycle** → **ADflow**: fan-exit P_t and T_t and required \dot{m} for 3500 hp
- **ADflow** → **pyCycle**: mass-averaged fan-face P_t and T_t
- GS and Broyden iterations implemented with OpenMDAO solvers

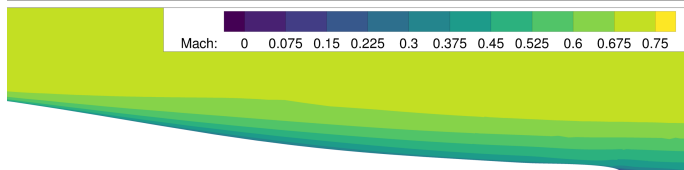
For any given FPR the propulsor is resized
and the mass-flow across the propulsor is balanced



FPR = 1.2



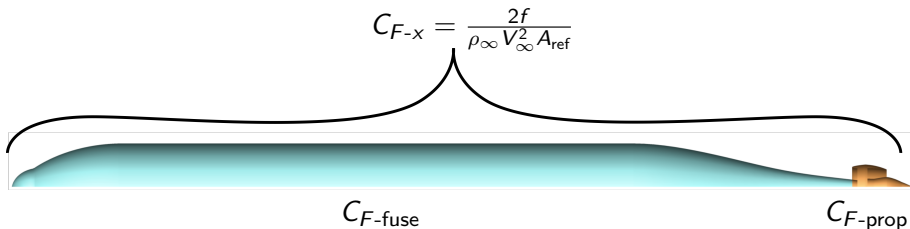
FPR = 1.35



baseline

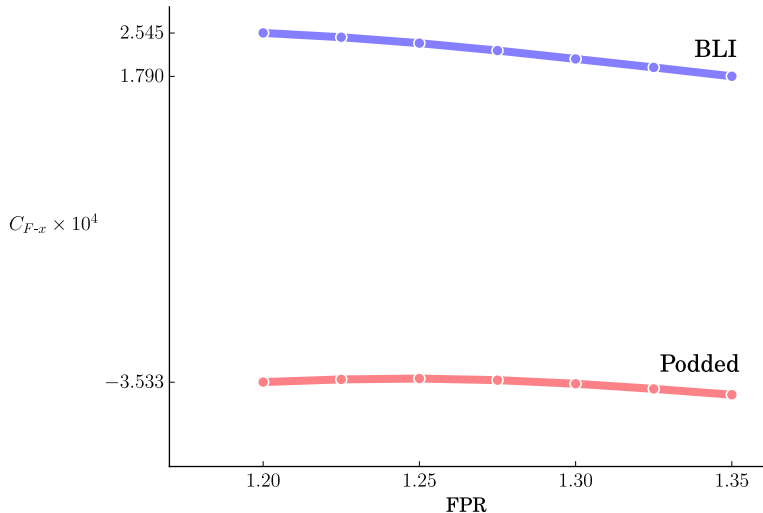


Performance is examined via net force coefficient

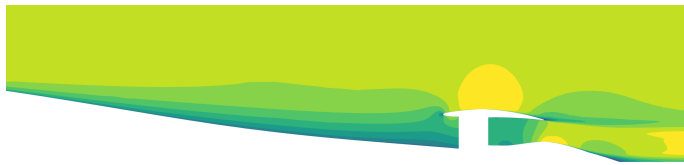


- $C_{F\text{-fuse}}$ should be negative, a decelerating force (i.e. drag)
- $C_{F\text{-prop}}$ should be positive, an accelerating force (i.e. thrust)
- C_{F-x} can be positive or negative

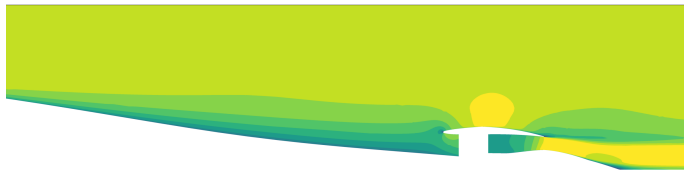
BLI offers 5 to 6 more force counts
for the same 3500 hp to the propulsor



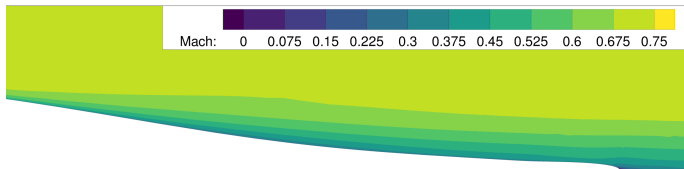
Propulsion-aerodynamic interactions cause the boundary layer height to vary with FPR



FPR = 1.2

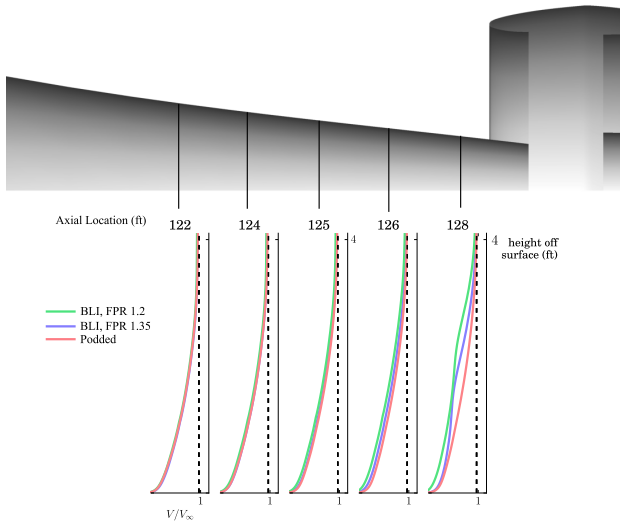


FPR = 1.35



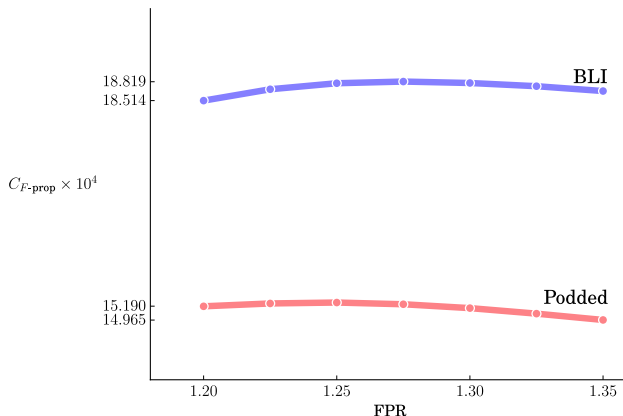
baseline

Propulsion-aerodynamic interactions cause the boundary layer height to vary with FPR



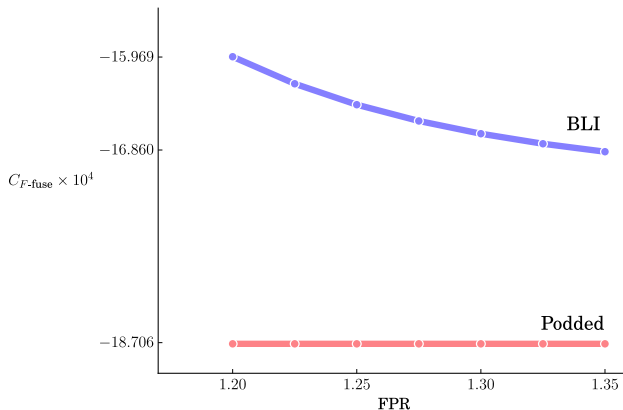
Improved propulsor performance accounts for 50-60% of the BLI performance gain

- Of the 5 to 6 total counts of improvement C_{F-x} , 3 counts come from increased C_{F-prop}

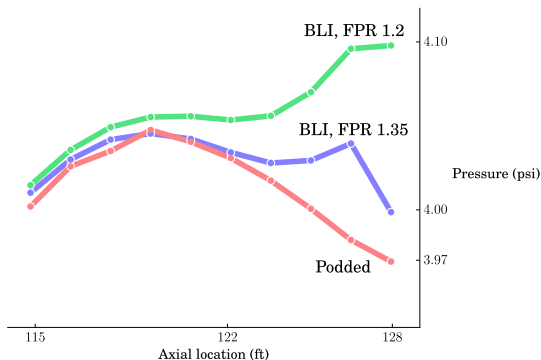


Fuselage drag reduction contributed 40-50% of the BLI performance gain

- Of the 5 to 6 total counts of improvement C_{F-x} , 2 to 3 counts come from smaller C_{F-fuse}



Reduction in C_{F-fuse} comes from an increased surface static pressure on the aft-fuselage



- the change in surface static pressure profile is a strong function of FPR

The performance gains from BLI come from a combination of propulsion and aerodynamic effects

- Capturing BLI effects requires a coupled simulation
- Aerodynamic effects are strongly influenced by inlet design and throttle setting



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Next step is to perform optimization of this configuration with propulsion and shape design variables

Thank you to:

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